



- SPaCIFY project - Synoptic : Spacecraft Synchronous DSML

Alexandre Cortier

Post-doc at IRIT/ACADIE

cortier@irit.fr



1. Introduction

2. Synoptic language

3. Middleware/Synoptic Interaction

4. Current works



SPaCIFY : ANR Project

Spacify ANR (French Research National Agency) Project

End : September 2009

■ Aim :

- ▶ R&D project aiming at developing a design environment for critical embedded software (Spacecraft System)
- ▶ Model-Driven Engineering and Formal Methods
 - model checking
 - formally-verified domain specific transformations
- ▶ multi-clock synchronous paradigm
- ▶ simulation and analysis tools
- ▶ scheduling analysis
- ▶ executive platform supporting distribution, partitionning and dynamic adaptation (middleware)

Environment components will be built upon the Topcased toolkit.
(*The Open-Source Toolkit for Critical Systems*)



The SPaCIFY Project

- Industrial Stakeholders :
 - ▶ CNES, Thales Alenia Space, EADS Astrium
 - spacecraft system designers
 - ▶ Anyware Technologies, GEENSYS
 - graphical design environment
 - configuration, versions and documentation management
- Academic Stakeholders :
 - ▶ IRIT-ACADIE (Toulouse): Synoptic language definition, formally-verified model transformations
 - ▶ ENSTB-CAMA (Brest) : middleware design
 - ▶ IRISA-ESPRESSO (Rennes) : synchronous semantics
 - ▶ LaBRI (Bordeaux) : model-checking



Synoptic

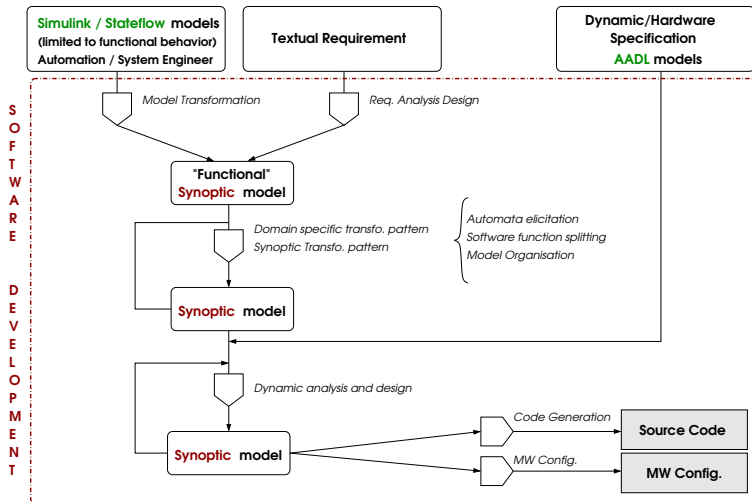
Synoptic : DSML (*Domain Specific Modeling Language*) for spacecraft systems.

Requirements :

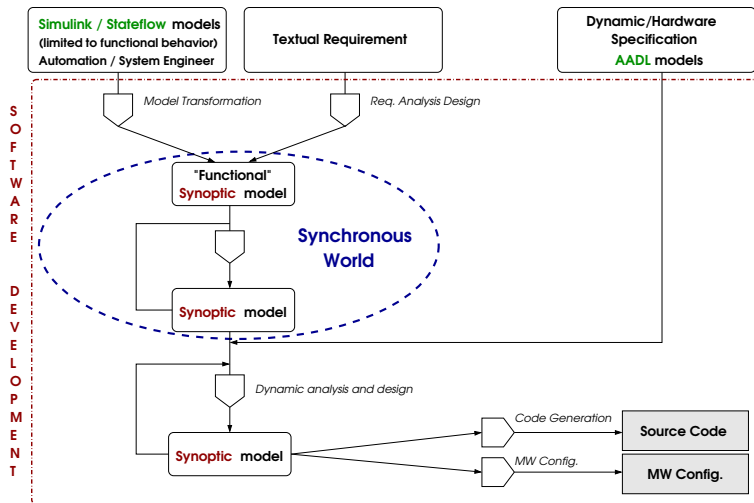
- central language of the development environment
- support an iterative and incremental development process
- functional, architectural and dynamic views specifications
- modular design
- based on a synchronous semantics (functional part)



Overview : SPaCIFY development process



Overview : SPaCIFY development process



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Synoptic

Synoptic :

- a graphical and textual DSML
- provides high-level constructions to handle
 - ▶ multi-layers description (various modelling aspect)
 - ▶ various granularity levels (iterative and refinement development)
 - ▶ modular approach
- based on a synchronous semantics.
 - ▶ formal and deterministic analysis and verification
 - ▶ refinement proof
 - ▶ transformation proof



Synoptic : multi-layers system specification

Synoptic is not fundamentally a new language but an integration of different sources and concepts.

Synoptic is inspired by several approaches :

- **Geneauto** : safe subset of the Simulink/Stateflow modelling language used for the development of certified safety critical embedded real time systems
- **AADL** : *Architecture Analysis & Design Language* (formerly Avionics Architecture Description Language)
- **Components Models** : CCM, Fractal



Synoptic : multi-layers system specification

■ Software Architecture : **Geneauto approach**

- ▶ structural feature : Dataflow models (“Blocks Diagrams”)
- ▶ behavioral feature : Control Flow models (“Finite States Machines”)
- ▶ real-time constraints : clock properties

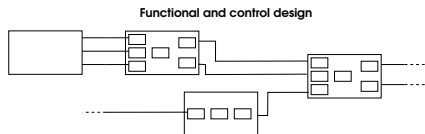
■ Dynamic/Hardware Architecture : **AADL approach**

- ▶ Threads description
- ▶ platform aspects (“components view”)
- ▶ mappings : which component execute which functional blocks ?
 - functional blocks → threads
 - threads → hardware components (processor)
 - signals → bus
 - variables → memory



Synoptic : multi-layers system specification

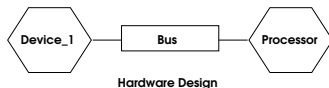
Software architecture



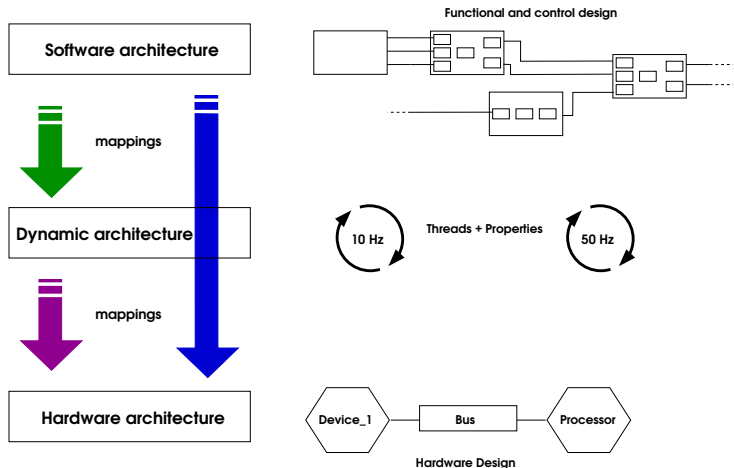
Dynamic architecture



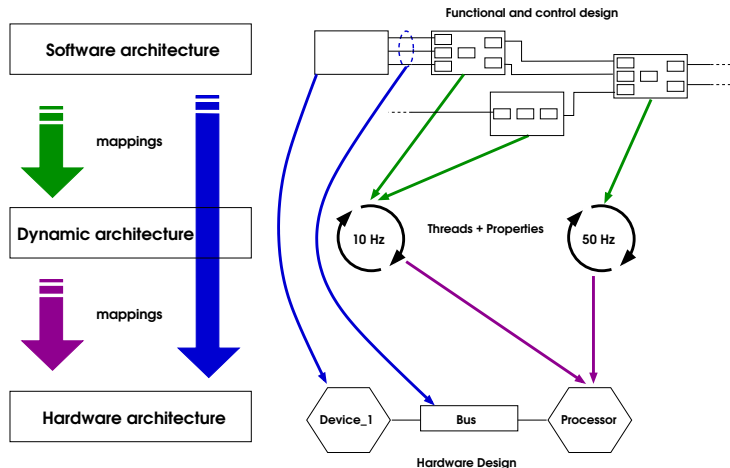
Hardware architecture



Synoptic : multi-layers system specification



Synoptic : multi-layers system specification



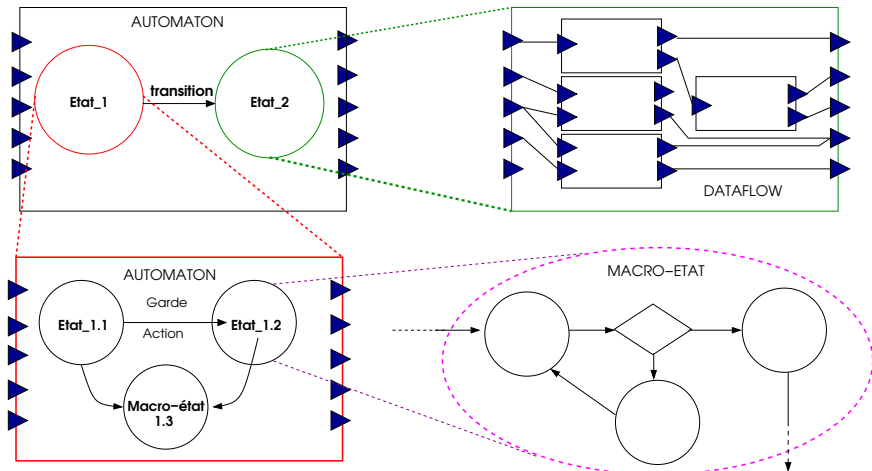
Synoptic : functional model

- Software architecture = blocks/nodes hierarchy
- A node in a block diagram has :
 - ▶ a **type**
 - ▶ several **implementations**
- a **node type** describes interaction ports (interface)
- different kinds of implementations :
 - ▶ **dataflow** : describes functional part
 - ▶ **automaton** : describes behavioral part (modes)
 - ▶ **external/primitive** : “black box”

Dataflow and automaton blocks are mutually nested.



Synoptic : functional model (block hierarchy)



Synoptic : functional model (node type)

Node type example :

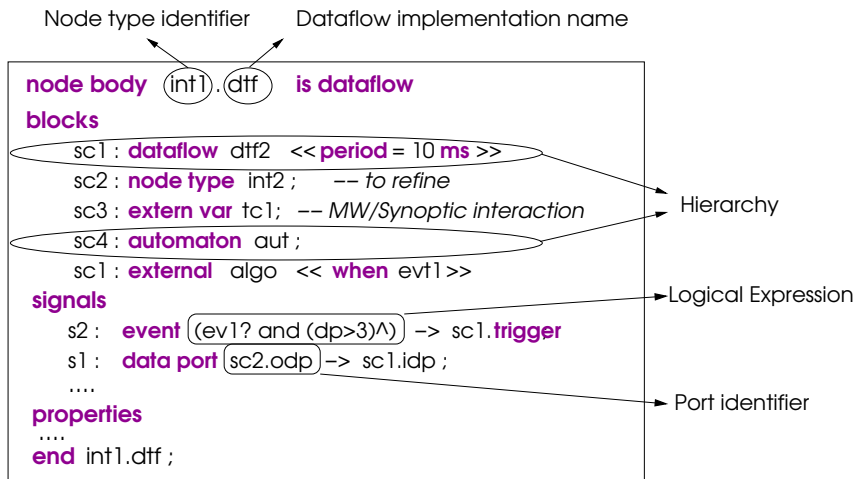
```
1 node type SunPointing
2 features
3 IMU_Data: in data port array 3 of double;
4 STR_Data: in data port array 4 of double;
5     DOR_Data: in data port array 4 of double;
6     MTQ_Cmd: out data port array 3 of double;
7     RW_Cmd: out data port array 3 of double;
8 end SunPointing;
```

Implicit ports :

- **reset** : re-initialization (boolean port)
- **trigger** : block activation (event port)
- **enable** : block activation control (boolean port)



Synoptic : functional model (**dataflow**)



Synoptic : functional model (automaton)

```

1  automaton INIT_calculateur.aut
2  states
3      PM_RESET: state dtf, /* dtf = datfalow implementation */
4      Bootstrap: state,
5      OBSW_running : state,
6      Firmware: macro state
7          states
8              PM_Built_IN_TESTS: state,
9              OBSW_checkers: state;
10             initial state PM_Built_IN_TESTS;
11             transitions
12                 tr1:PM_Built_IN_TESTS -[ ]→OBSW_checkers;
13         end Firmware,
14     RAM: macro state [...] end RAM;
15     initial state PM_RESET;
16     transitions
17         t1 : PM_RESET -[on G do A ]→ Firmware.PM_Built_IN_TESTS;
18         t2 : Firmware.PM_Built_IN_TESTS -[ ]→Firmware.OBSW_checkers;
19         [...]
20 end INIT_calculateur.aut;

```



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Synoptic/MW : external variables

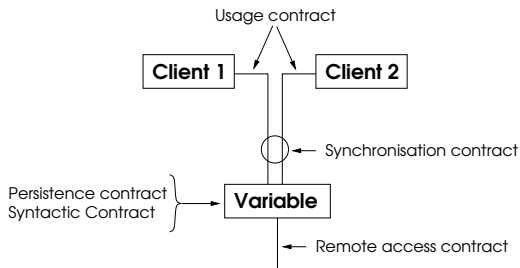
The Middleware has to abstract the asynchronous behavior of the system (bufferisation,...)

Interactions between MW and Synoptic models are handled using **external variables** concept.

- external variables = sources / sinks of signals
- external variables types :
 - ▶ constants, TM, TC, global variables,
- external variables contracts



Synoptic/MW : external variables



External variables and associated contracts are used to configure the MW



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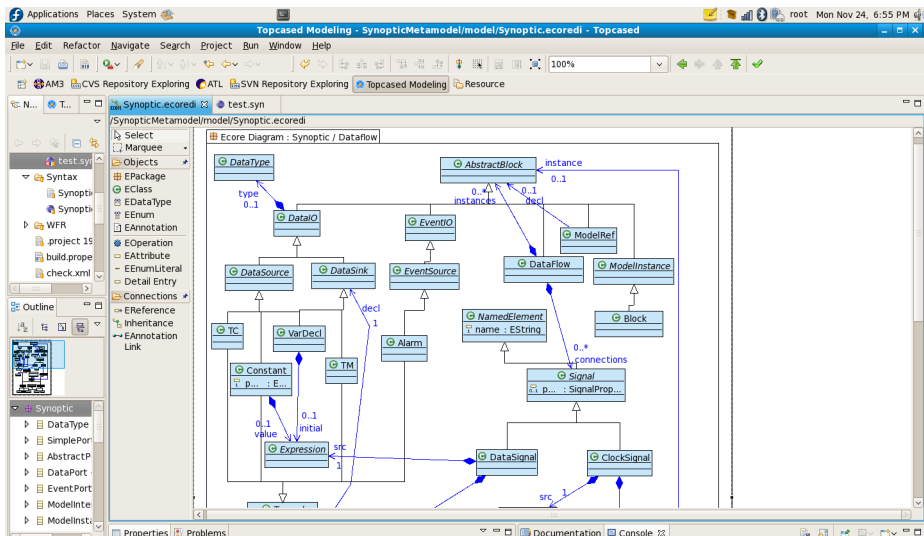


Synoptic Language Definition

- Synoptic Language Definition
 - ▶ Meta-Model definition (last steps)
 - ▶ concrete textual syntax
- Synoptic Semantics ?
 - ▶ in progress...
 - ▶ semantics by traduction (IRISA-ESPRESSO) : Signal (Polychrony)
 - ▶ we need to define a semantics for the language core
 - works on transformations proof (Martin Streker)



Meta-Model Ecore



Textual Syntax and Edition tool (Topcased)

```

block type nary_fun
features
  input[*]: in data port integer;
  output: out data port integer;
end nary_fun;

dataflow nary_fun.sum
blocks
  it: block type iterator;
  f: external add;
signals
  data 0 -> it.init;
  data input -> it.input;
  data it.elem -> f.x;
  data it.old -> f.y;
  data f.z -> it.new;
  data false -> it.stop;
  data it.output -> output;
end nary_fun.sum;

external nary_fun.function_c
properties
  path = "...";
  swct = 10 ms;
end nary_fun.function_c;
end externals;

package LIB
provides
  package ARITH
provides
  block type nary
  features
    input[*]: in data port integer;
    output: out data port integer;
  end nary;

```

Transformations Validation

- Automatic mappings : blocks \rightarrow threads
 - ▶ to assist the developer
 - ▶ need a formalisation of current pragmatic rules used by system engineers
- Blocks and Signals Refinements :
 - ▶ automatic refinement (patterns : validated transformation)
 - ▶ Proof Obligation (PO) generation for manual refinements
- Edition transformations :
 - ▶ ex : Model organisation, Software function splitting
 - ▶ Automatic and validated transformations



Questions ?

Questions ?

